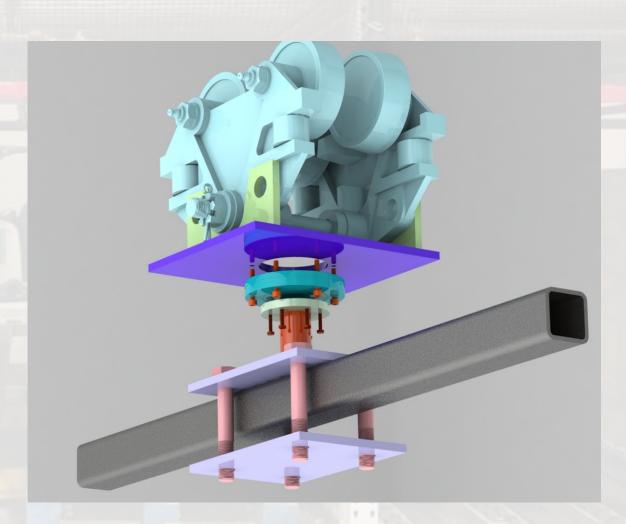


Final Design

Our goal: assembly of a safe and functional track mounted arm able to house recommended vacuum lift system



Project Status

- Main components assembled
- After assembly, arm rotation test was deemed unnecessary
- Other design issues found upon assembly



Project Status

- A number of design modifications to implement
- Minimal procurement left

	Display Week:	18		Feb 24, 2020	Mar 2, 2020	Mar 9, 2020	Mar 16, 2020	Mar 23, 2020	Mar 30, 2020
	ASSIGNED			#####1	2 3 4 5 6 7 8	9 10 11 12 13 14 15			# 31 1 2 3 4 5 6
TASK	TO	START	END	MTVTFSS	M T W T F S S	M T W T F S S	M T W T F S S	MTVTFSS	MTWTFSSM
3.3.2. Trolley Stabilizer Designed	EPF	2/28/20	3/5/20						
3.3.3. Vacuum Design	RF, RU, PK	2/28/20	3/4/20						
4. Detailed Design Review		2/29/20	4/3/20						
4.1. Detailed Design Review Report	All								
4.1.1. Create DDR	All	3/4/20	3/9/20						
4.1.2. Create DDR Presentation	EPF	3/9/20	3/11/20						
4.1.3. Update Client	PK	3/11/20	3/12/20						
4.2. Final Modifications to Design									
4.2.1. Design Limit Switch Modification		3/9/20	3/11/20						
4.2.2. Build Trolley Stabilizer		3/10/20	3/12/20						
4.2.2. Vacuum Hand Design		3/9/20	3/11/20						
4.2.3. Arm Lock Design		3/9/20	3/11/20						
4.2.4. Trolley Lock Design		3/9/20	3/11/20						
4.3. Prototype Release									
4.3.1. Final Detailed Design		3/16/20	3/30/20						
4.3.2.									
4.3.1. Operational Prototype									

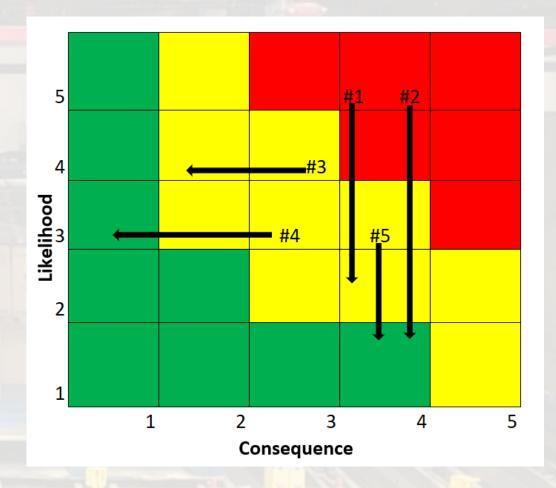
Project Status

While budget was unspecified, goal was below \$5,000

Total	\$1,649.52		
Suction	\$228.01		
Hardware	\$218.97		
Pivot Point	\$426.97		
Track, Trolley, and Arm	\$775.57		

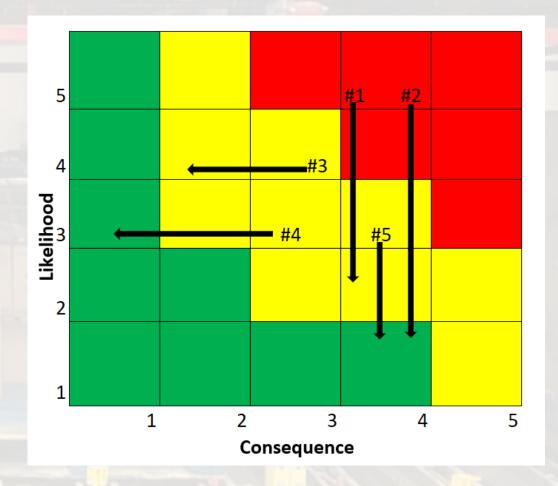
Risk Management

- Risk 1: Excessive beam deflection
 - Solution: ran Solidworks simulations using various materials
- Risk 2: Extreme shear forces on turntable
 - Solution: implemented heavy duty slew bearing rated higher than necessary
- Risk 3: Pinch points
 - Solution: protective casing and locks on movable parts



Risk Management

- Risk 4: Uneven distribution of vacuum head weight
 - Solution: position cups on secure frame
- Risk 5: Lack of suction while picking up items
 - Solution: adequate force applied to suction cups with weight of frame and correct pressure



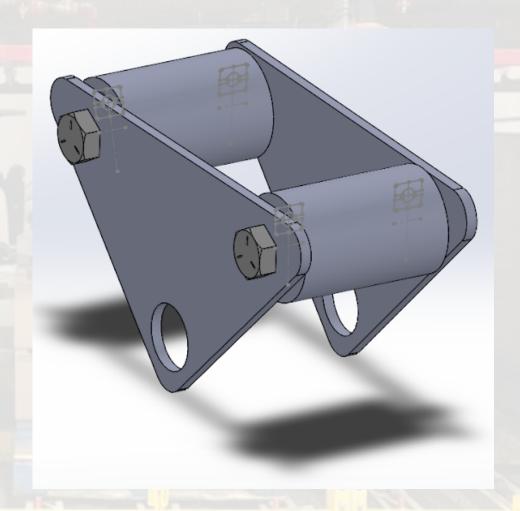
Final Design Additions – Trolley Stabilization

- Upon testing, it was noticed the trolley tilted as a result of an off centred load
- Not unsafe but appeared awkward



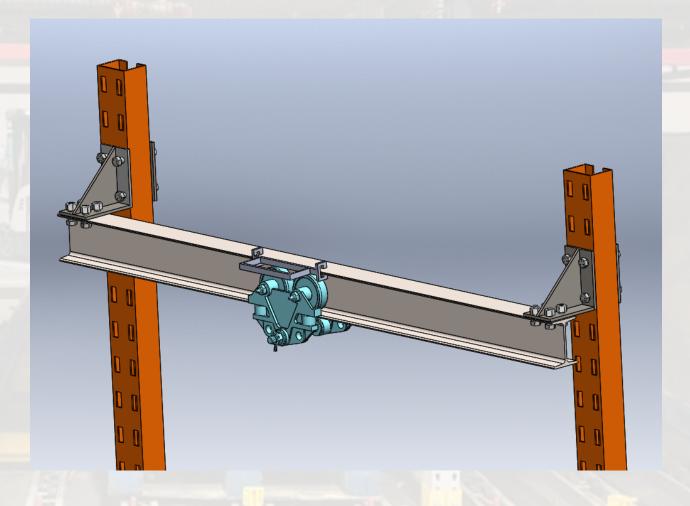
Final Design Additions – Trolley Stabilization

- A stabilizer piece was designed
- Two rollers pressed lightly against the bottom of the beam to support trolley without limiting movement



Final Design Additions – Safety Locks

- A lock for the trolley will be installed to prevent unintentional sliding
- A lock for the arm will be installed to prevent unintentional swinging



Prototype Testing - Vacuum Suction

- Air flow from single pump split into two suction cups
- Vacuum tested on cardboard (with and without tape) and pails





Final Design Recommendations

- An optimized suction system will be determined based on testing conducted
- Our recommendation: An optimized version of our testing or an off-theshelf vacuum automation system

